Select poses to use for calibration ([]=all):

[1 2 3 4 5 6 7 8 9 10 11 12 17 18 19 20 21 22 23 24 25 27 28 29 30 31 32 33 34 35 39 40 41 42 44 45 48 ]

Color internals:

Focal length: [1068.63 1073.63]

Principal point: [642.88 464.59]

Distortion: [0.0138 -0.0124 -0.0077 -0.0002 0.0000]

Relative pose:

Rotation: [1.00000 0.00000 0.00000;

0.00000 1.00000 0.00000;

0.00000 0.00000 1.00000]

Translation: [0.00000 0.00000 0.00000]

Depth internals:

Focal length: [590.14 590.03]

Principal point: [320.08 230.00]

Distortion: [0.0000 0.0000 0.0000 0.0000 0.0000]

Depth params: [1.32 -0.000298]

Depth distortion alpha: [0.0000 0.0000]

Relative pose:

Rotation: [0.99987 0.01557 0.00291;

-0.01576 0.99657 0.08122;

-0.00164 -0.08125 0.99669]

Translation: [-0.05060 -0.15543 -0.39927]